

6.641 Electromagnetic Fields, Forces, and Motion
Spring 2009

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Lecture 3: Electroquasistatic and Magnetoquasistatic Fields and Boundary Conditions

I. Conditions for Electroquasistatic Fields

A. Order of Magnitude Estimate [Characteristic Length L , Characteristic time τ]

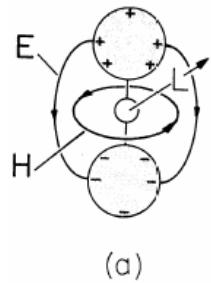


Figure 3.3.1 Prototype systems involving one typical length. (a) EQS system in which source of EMF drives a pair of perfectly conducting spheres having radius and spacing on the order of L .

Courtesy of Hermann A. Haus and James R. Melcher. Used with permission.

$$\nabla \cdot \bar{E} = \rho/\epsilon \Rightarrow \frac{E}{L} = \rho/\epsilon \Rightarrow E = \frac{\rho L}{\epsilon}$$

$$\nabla \times \bar{H} = \epsilon \frac{\partial \bar{E}}{\partial t} \Rightarrow \frac{H}{L} = \frac{\epsilon E}{\tau} \Rightarrow H = \frac{\epsilon E L}{\tau} = \frac{L^2 \rho}{\tau}$$

$$\nabla \times \bar{E} = -\mu \frac{\partial \bar{H}}{\partial t} \Rightarrow \frac{E_{\text{error}}}{L} = \frac{\mu H}{\tau} = \frac{\mu \rho L^2}{\tau^2} \Rightarrow E_{\text{error}} = \frac{\mu \rho L^3}{\tau}$$

$$\frac{E_{\text{error}}}{E} = \frac{\mu \rho L^3}{\tau \rho L} \epsilon = \frac{\mu \epsilon L^2}{\tau^2} = \frac{L^2}{(c\tau)^2} \quad ; \quad c = \frac{1}{\sqrt{\epsilon \mu}}$$

$$\frac{E_{\text{error}}}{E} \ll 1 \Rightarrow \frac{L}{c\tau} \ll 1$$

B. Estimate of Error introduced by EQS approximation

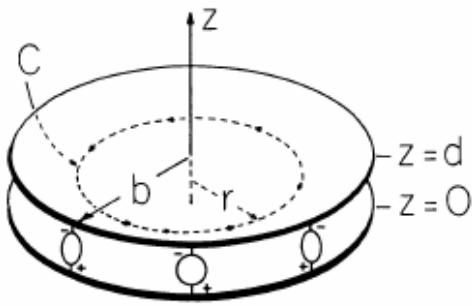


Figure 3.3.2 Plane parallel electrodes having no resistance, driven at their outer edges by a distribution of sources of EMF.

Courtesy of Hermann A. Haus and James R. Melcher. Used with permission.

$$\bar{E} = \frac{V}{d} \bar{I}_z = E_0 \bar{I}_z$$

$$\sigma_{su} = \begin{cases} -\epsilon E_0 & z = d \\ +\epsilon E_0 & z = 0 \end{cases}$$

$$K_r 2\pi b + \pi b^2 \frac{d\sigma_{su}}{dt} = 0 \Rightarrow K_r = -\frac{b}{2} \frac{d\sigma_{su}}{dt} = -\frac{b}{2} \epsilon \frac{dE_0}{dt}$$

$$\oint_C \bar{H} \cdot d\bar{s} = \int_S \frac{\partial}{\partial t} (\epsilon \bar{E}) \cdot d\bar{a} \Rightarrow H_\phi 2\pi r = \pi r^2 \epsilon \frac{dE_0}{dt} \Rightarrow H_\phi = \frac{r}{2} \epsilon \frac{dE_0}{dt}$$

$$\oint_C \bar{E} \cdot d\bar{s} = - \int_S \mu \frac{\partial \bar{H}}{\partial t} \cdot d\bar{a}$$

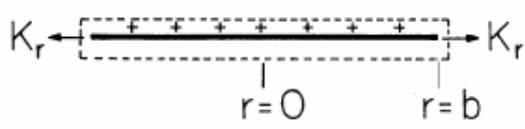


Figure 3.3.3 Parallel plates of Figure 3.3.2, showing volume containing lower plate and radial surface current density at its periphery.

Courtesy of Hermann A. Haus and James R. Melcher. Used with permission.

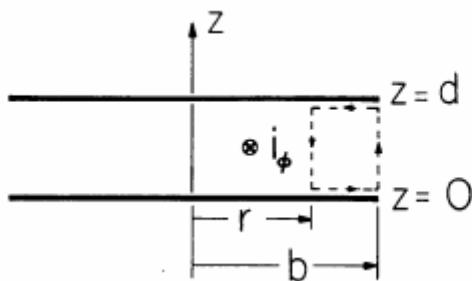


Figure 3.3.4 Cross-section of system shown in Figure 3.3.2 showing surface and contour used in evaluating correction \mathbf{E} field.

Courtesy of Hermann A. Haus and James R. Melcher. Used with permission.

$$[E_z(b) - E_z(r)]d = + \frac{\mu\epsilon}{2} \int_r^b r' dr' d \frac{d^2 E_0}{dt^2}$$

$$= \frac{\mu\epsilon d}{4} (b^2 - r^2) \frac{d^2 E_0}{dt^2}$$

$$E_z(r) = E_0 + \frac{\epsilon\mu}{4} \frac{d^2 E_0}{dt^2} (r^2 - b^2)$$

If $E_0(t) = A \cos \omega t$

$$\frac{|E_{\text{error}}|}{E_0} = \frac{\epsilon\mu}{4E_0} \frac{d^2 E_0}{dt^2} (b^2 - r^2) = \frac{1}{4} \omega^2 \epsilon\mu (b^2 - r^2)$$

$$\frac{|E_{\text{error}}|}{E_0} \ll 1 \Rightarrow \frac{\omega^2 \epsilon\mu b^2}{4} \ll 1$$

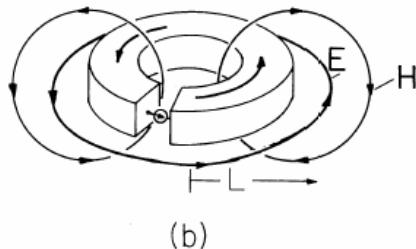
$$f\lambda = c = \frac{1}{\sqrt{\epsilon\mu}}$$

$$\frac{\omega}{2\pi} \lambda = c \Rightarrow \omega = \frac{2\pi c}{\lambda} \Rightarrow \frac{\omega^2 \epsilon\mu b^2}{4} = \frac{\pi^2}{\lambda^2} b^2 \ll 1 \Rightarrow b \ll \frac{\lambda}{\pi}$$

$$f=1 \text{ MHz in free space} \Rightarrow \lambda = \frac{3 \times 10^8}{10^6} = 300 \text{ m}$$

If $b \ll 100 \text{ m}$ EQS approximation is valid.

II. Conditions for Magnetoquasistatic Fields



(b) MQS system consisting of perfectly conducting loop driven by current source. The radius of the loop and diameter of its cross-section are on the order of L .

Courtesy of Hermann A. Haus and James R. Melcher. Used with permission.

$$\nabla \times \bar{H} = \bar{J} \Rightarrow \frac{H}{L} = J \Rightarrow H = JL$$

$$\nabla \times \bar{E} = -\mu \frac{\partial \bar{H}}{\partial t} \Rightarrow \frac{E}{L} = \frac{\mu H}{\tau} \Rightarrow E = \frac{\mu H L}{\tau} = \frac{\mu J L^2}{\tau}$$

$$\nabla \times \bar{H}_{\text{error}} = \epsilon \frac{\partial \bar{E}}{\partial t} \Rightarrow \frac{\bar{H}_{\text{error}}}{L} = \frac{\epsilon E}{\tau} \Rightarrow H_{\text{error}} = \frac{\epsilon E L}{\tau^2} = \frac{\epsilon \mu J L^3}{\tau^2}$$

$$\frac{H_{\text{error}}}{H} = \frac{\epsilon \mu J L^3}{\tau^2 J L} = \frac{\epsilon \mu L^2}{\tau^2} = \frac{L^2}{(c\tau)^2} \ll 1 \Rightarrow L \ll c\tau$$

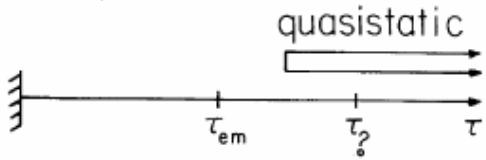


Figure 3.4.1 Range of characteristic times over which quasistatic approximation is valid. The transit time of an electromagnetic wave is τ_{em} while $\tau_?$ is a time characterizing the dynamics of the quasistatic system.

Courtesy of Hermann A. Haus and James R. Melcher. Used with permission.

$$\tau_{\text{em}} = \frac{L}{c} = L\sqrt{\epsilon\mu}$$

III. Boundary Conditions

1. Gauss' Continuity Condition

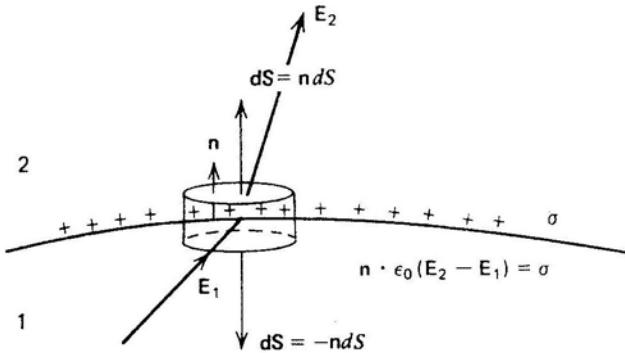


Figure 2-19 Gauss's law applied to a differential sized pill-box surface enclosing some surface charge shows that the normal component of $\epsilon_0 \mathbf{E}$ is discontinuous in the surface charge density.

$$\oint_S \epsilon_0 \bar{E} \cdot d\bar{a} = \int_S \sigma_s dS \Rightarrow \epsilon_0 (E_{2n} - E_{1n}) dS = \sigma_s dS$$

$$\epsilon_0 (E_{2n} - E_{1n}) = \sigma_s \Rightarrow \bar{n} \cdot [\epsilon_0 (\bar{E}_2 - \bar{E}_1)] = \sigma_s$$

2. Continuity of Tangential \bar{E}

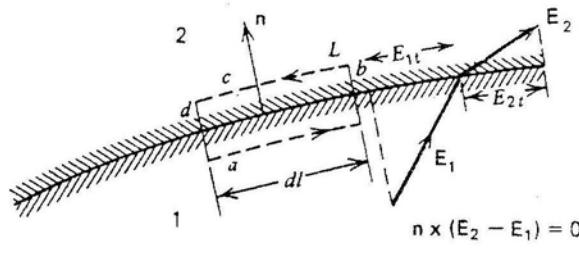


Figure 3-12 (a) Stokes' law applied to a line integral about an interface of discontinuity shows that the tangential component of electric field is continuous across the boundary.

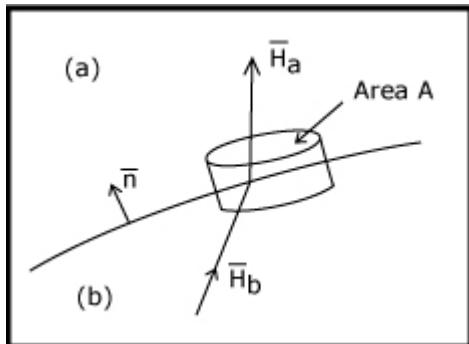
$$\oint_C \bar{E} \cdot d\bar{s} = (E_{1t} - E_{2t}) dl = 0 \Rightarrow E_{1t} - E_{2t} = 0$$

$$\bar{n} \times (\bar{E}_1 - \bar{E}_2) = 0$$

Equivalent to $\Phi_1 = \Phi_2$ along boundary

3. Normal \bar{H}

$$\oint_S \mu_0 \bar{H} \cdot d\bar{a} = 0$$



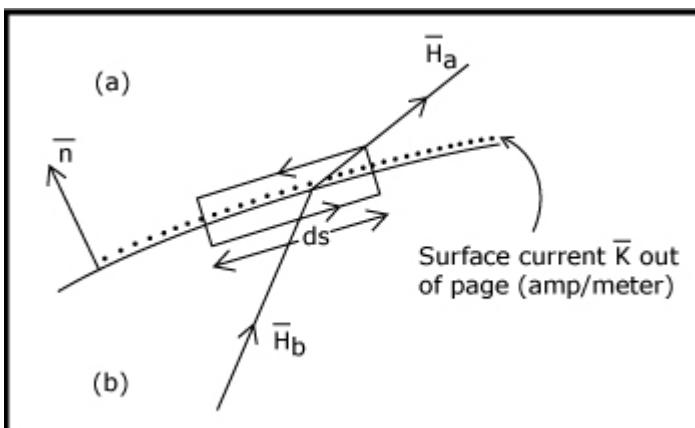
$$\mu_0 (H_{an} - H_{bn}) A = 0$$

$$H_{an} = H_{bn}$$

$$\bar{n} \cdot [\bar{H}_a - \bar{H}_b] = 0$$

4. Tangential \bar{H}

$$\oint_C \bar{H} \cdot d\bar{s} = \int_S \bar{J} \cdot d\bar{a} + \frac{d}{dt} \int_S \epsilon_0 \bar{E} \cdot d\bar{a}$$

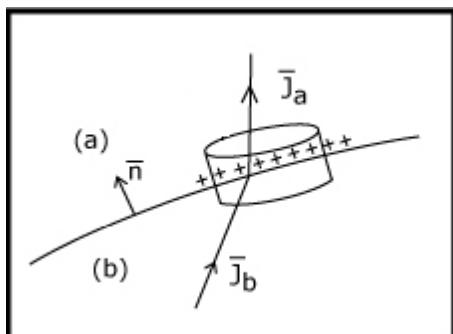


$$H_{bt} ds - H_{at} ds = K ds$$

$$H_{bt} - H_{at} = K$$

$$\bar{n} \times [\bar{H}_a - \bar{H}_b] = \bar{K}$$

5. Conservation of Charge Boundary Condition

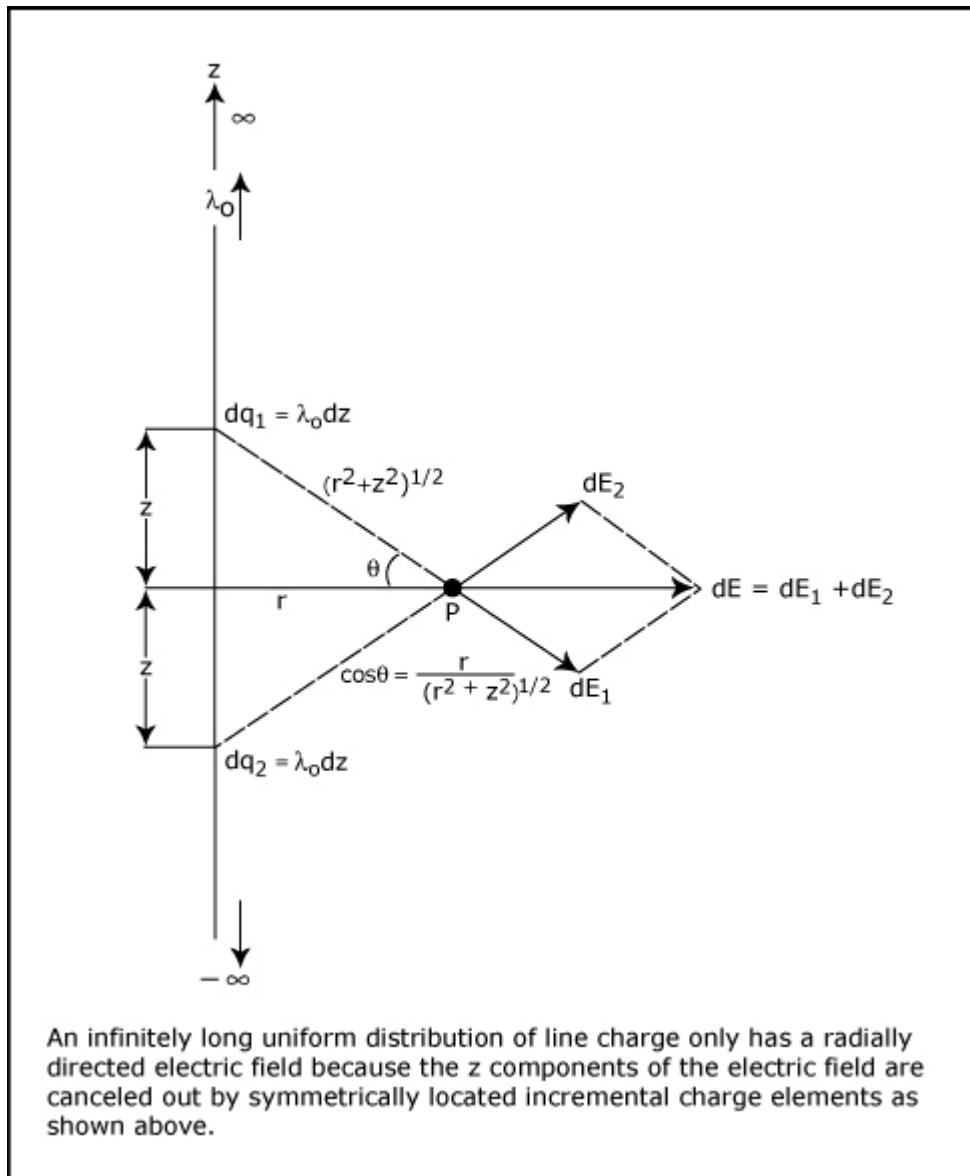


$$\oint_S \bar{J} \cdot d\bar{a} + \frac{d}{dt} \int_V \rho dV = 0$$

$$\bar{n} \cdot [\bar{J}_a - \bar{J}_b] + \frac{\partial}{\partial t} \sigma_s = 0$$

6. Electric Field from a Sheet of Surface Charge

a. Electric Field from a Line Charge



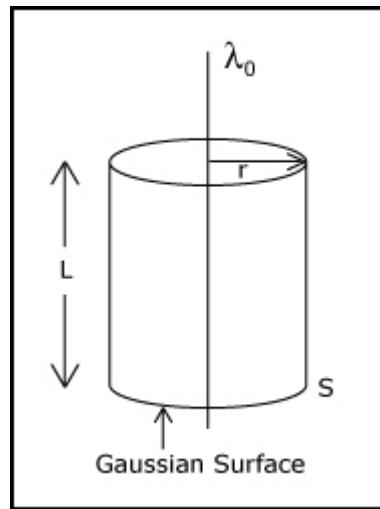
$$dE_r = \frac{dq}{4\pi\epsilon_0 (r^2 + z^2)} \cos\theta = \frac{\lambda_0 r dz}{4\pi\epsilon_0 (r^2 + z^2)^{3/2}}$$

$$E_r = \int_{z=-\infty}^{+\infty} dE_r = \frac{\lambda_0 r}{4\pi\epsilon_0} \int_{z=-\infty}^{+\infty} \frac{dz}{(r^2 + z^2)^{3/2}}$$

$$= \frac{\lambda_0 r}{4\pi\epsilon_0} \frac{z}{r^2 (z^2 + r^2)^{1/2}} \Big|_{z=-\infty}^{+\infty}$$

$$= \frac{\lambda_0}{2\pi\epsilon_0 r}$$

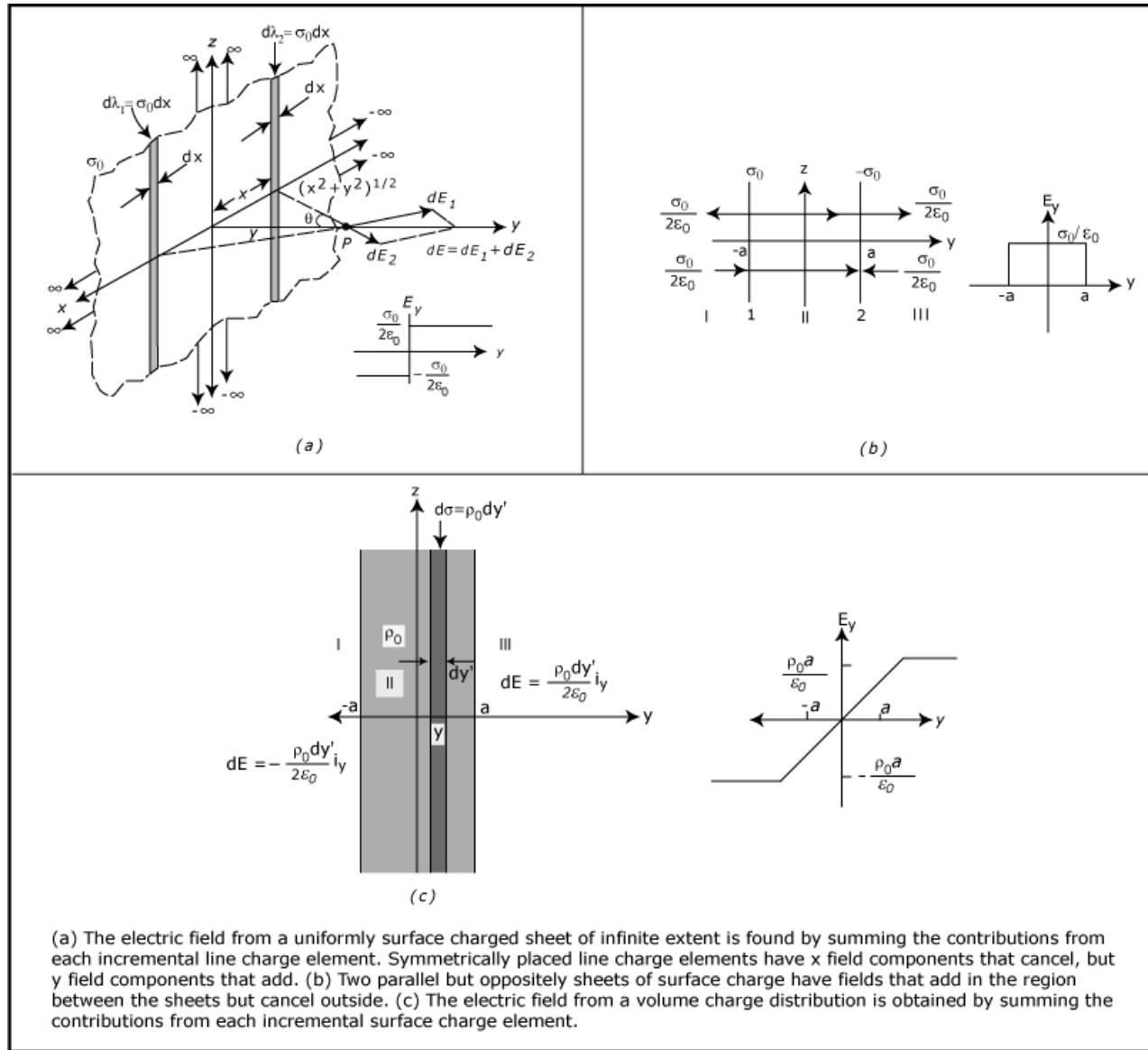
Another way: Gauss' Law



$$\int_S \epsilon_0 \bar{E} \cdot d\bar{a} = \epsilon_0 E_r 2\pi r L = \lambda_0 L$$

$$E_r = \frac{\lambda_0}{2\pi\epsilon_0 r}$$

b. Electric Field from a Sheet Charge



(a) The electric field from a uniformly surface charged sheet of infinite extent is found by summing the contributions from each incremental line charge element. Symmetrically placed line charge elements have x field components that cancel, but y field components that add. (b) Two parallel but oppositely sheets of surface charge have fields that add in the region between the sheets but cancel outside. (c) The electric field from a volume charge distribution is obtained by summing the contributions from each incremental surface charge element.

$$dE_y = \frac{d\lambda}{2\pi\epsilon_0 (x^2 + y^2)^{1/2}} \cos \theta = \frac{\sigma_0 y dx}{2\pi\epsilon_0 (x^2 + y^2)}$$

$$E_y = \int_{x=-\infty}^{+\infty} dE_y = \frac{\sigma_0 y}{2\pi\epsilon_0} \int_{x=-\infty}^{+\infty} \frac{dx}{x^2 + y^2}$$

$$= \frac{\sigma_0 y}{2\pi\epsilon_0} \frac{1}{y} \tan^{-1} \frac{x}{y} \Big|_{-\infty}^{+\infty}$$

$$= \begin{cases} \frac{\sigma_0}{2\epsilon_0} & y > 0 \\ -\frac{\sigma_0}{2\epsilon_0} & y < 0 \end{cases}$$

Checking Boundary condition at $y=0$

$$E_y(y=0_+) - E_y(y=0_-) = \frac{\sigma_0}{\epsilon_0}$$

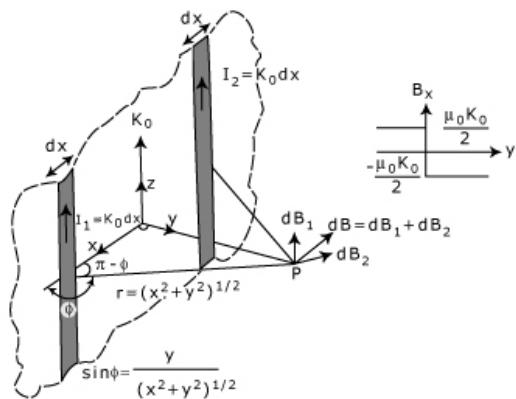
$$\frac{\sigma_0}{2\epsilon_0} - \left(-\frac{\sigma_0}{2\epsilon_0} \right) = \frac{\sigma_0}{\epsilon_0}$$

c. Two sheets of Surface Charge (Capacitor)

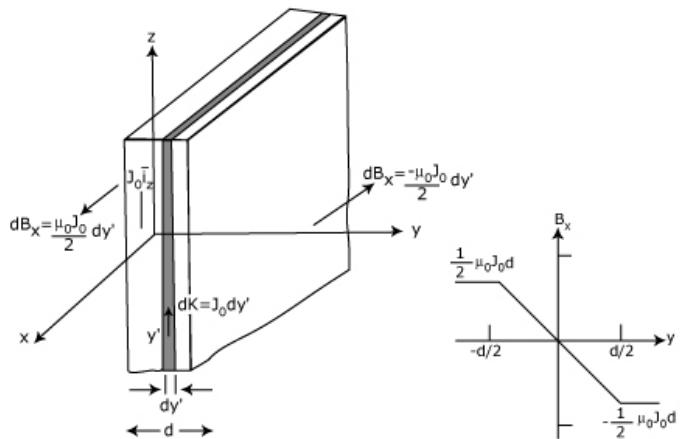
$$\bar{E}_1 = \begin{cases} \frac{\sigma_0}{2\epsilon_0} \bar{i}_y & y > -a \\ -\frac{\sigma_0}{2\epsilon_0} \bar{i}_y & y < -a \end{cases}, \quad \bar{E}_2 = \begin{cases} -\frac{\sigma_0}{2\epsilon_0} \bar{i}_y & y > a \\ \frac{\sigma_0}{2\epsilon_0} \bar{i}_y & y < a \end{cases}$$

$$\bar{E} = \bar{E}_1 + \bar{E}_2 = \begin{cases} \frac{\sigma_0}{\epsilon_0} \bar{i}_y & |y| < a \\ 0 & |y| > a \end{cases}$$

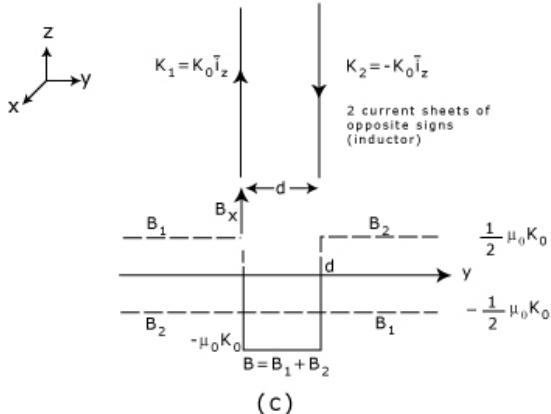
7. Magnetic Field from a Sheet of Surface Current



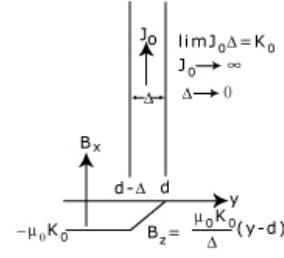
(a)



(b)



(c)



(d)

A uniform surface current of infinite extent generates a uniform magnetic field oppositely directed on each side of the sheet. The magnetic field is perpendicular to the surface current but parallel to the plane of the sheet. (b) The magnetic field due to a slab of volume current is found by superimposing the fields due to incremental surface currents. (c) Two parallel but oppositely directed surface current sheets have fields that add in the region between the sheets but cancel outside the sheet. (d) The force on a current sheet is due to the average field on each side of the sheet as found by modeling the sheet as a uniform volume current distributed over an infinitesimal thickness Δ .

From a line current I

$$H_\phi = \frac{I}{2\pi r}$$

$$\bar{i}_\phi = -\sin\phi \bar{i}_x + \cos\phi \bar{i}_y$$

Thus from 2 symmetrically located line currents

$$dH_x = \frac{dI}{2\pi(x^2 + y^2)^{1/2}} (-\sin\phi)$$

$$= -\frac{K_0 dx}{2\pi} \frac{y}{x^2 + y^2}$$

$$H_x = -\frac{K_0}{2\pi} y \int_{x=-\infty}^{+\infty} \frac{dx}{x^2 + y^2}$$

$$= -\frac{K_0 y}{2\pi} \frac{1}{y} \tan^{-1} \frac{x}{y} \Big|_{x=-\infty}^{+\infty}$$

$$= \begin{cases} -\frac{K_0}{2} & y > 0 \\ +\frac{K_0}{2} & y < 0 \end{cases}$$

Check boundary condition at $y=0$:

$$H_x(y=0_+) - H_x(y=0_-) = -K_0$$

$$-\frac{K_0}{2} - \left(\frac{K_0}{2} \right) = -K_0$$